

EXISTENCE RESULTS FOR BOUNDARY - VALUE PROBLEMS WITH NONLINEAR FRACTIONAL DIFFERENTIAL INCLUSIONS AND INTEGRAL CONDITIONS

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ABSTRACT . In this article , the authors establish sufficient conditions for the
 existence of solutions for a class of boundary value problem for fractional
 differential inclusions involving the Caputo fractional derivative and nonlinear
 integral conditions . Both cases of convex and nonconvex valued right hand
 sides are considered . The topological structure of the set of solutions also
 examined .

1 . INTRODUCTION

This article concerns the existence and uniqueness of solutions of the boundary
 value problem (BVP for short) with fractional order differential inclusions and
 nonlinear integral conditions of the form

$${}_CD^\alpha y(t) \in F(t, y), \quad \text{for a . e . } t \in J = [0, T], \quad 1 < \alpha \leq 2, \quad (1.1)$$

$$y(0) - y'(0) = \int_0^T g(s, y) ds, \quad (1.2)$$

$$y(T) + y'(T) = \int_0^T h(s, y) ds, \quad (1.3)$$

where ${}_CD^\alpha$ is the Caputo fractional derivative , $F : J \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is a multivalued
 map , $(\mathcal{P}(\mathbb{R}))$ is the family of all nonempty subsets of \mathbb{R} , and $g, h : J \times$
 $\mathbb{R} \rightarrow \mathbb{R}$ are given continuous functions . Differential equations of fractional order
 have recently proved to be valuable tools in the modelling of many phenomena in various
 fields of science and engineering . There are numerous applications to problems in
 viscoelasticity , electro chemistry , control , porous media , electromagnetics ,
 etc .

(see [20 , 30 , 31 , 34 , 40 , 41 , 45]) . There has been a significant
 development in ordinary and partial differential equations involving both Riemann -
 Liouville and Caputo fractional derivatives in recent years ; see the monographs of
 Kilbas *e t al* .

[38] , Miller and Ross [42] , Samko *e t al* . [50] and the papers of Agarwal *e t al* .
 [2] , Benchohra *e t al* . [8] , Benchohra and Hamani [9] , Daftardar - Gejji and
 Jafari

[17] , Delbosco and Rodino [19] , Diethelm *e t al* . [20 , 21 , 22] , El - Sayed [23 , 24 , 25] ,

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Furati and Tatar [28 , 29] , Kaufmann and Mboumi [36] , Kilbas and Marzan [37] , Mainardi [40] , Momani and Hadid [43] , Momani *e t al .* [44] , Ouahab [46] , Podlubny

e t al . [49] , Yu and Gao [52] and the references therein . In [7 , 12] the authors studied the existence and uniqueness of solutions of classes of initial value problems for functional differential equations with infinite delay and fractional order , and in [6] a class of perturbed functional differential equations involving the Caputo fractional derivative has been considered . Related problems to (1 . 1) – (1 . 3) have been considered by means of different methods by Belarbi *e t al .* [5] and Benchohra *e t al .* in [10 , 11] in the case of $\alpha = 2$.

Applied problems require definitions of fractional derivatives allowing the utilization of physically interpretable initial conditions that contain $y(0), y'(0)$, etc . , and the same is true for boundary conditions . Caputo ' s fractional derivative satisfies these demands . For more details on the geometric and physical interpretation for fractional derivatives of both Riemann - Liouville and Caputo types see [33 , 48] . The web site [http : / / people . t u k e . s k / i g o r . p o d l u b n y /](http://people.tuke.sk/igor.podlubny/) authored by Igor Podlubny contains more information on fractional calculus and its applications , and hence it is very useful for those interested in this field .

Boundary value problems with integral boundary conditions constitute a very interesting and important class of problems . They include two , three , multipoint , and nonlocal boundary value problems as special cases . Integral boundary conditions appear in population dynamics [13] and cellular systems [1] .

This paper is organized as follows . In Section 2 , we introduce some preliminary results needed in the following sections . In Section 3 , we present an existence result for the problem (1 . 1) – (1 . 3) when the right hand side is convex valued by using the nonlinear alternative of Leray - Schauder type . In Section 4 , two results are given for nonconvex valued right hand sides . The first one is based upon a fixed point theorem for contraction multivalued maps due to Covitz and Nadler [16] , and the second one on the nonlinear alternative of Leray Schauder type [32] for single - valued maps , combined with a selection theorem due to Bressan - Colombo [14] (also see [27]) for lower semicontinuous multivalued maps with decomposable values . The topological structure of the solutions set is considered in Section 5 . An example is presented in the last section . These results extend to the multivalued case some results from the above cited literature , and constitute a new contribution to this emerging field of research .

2 . PRELIMINARIES

In this section , we introduce notation , definitions , and preliminary facts that will be used in the remainder of this paper . Let $C(J, \mathbb{R})$ be the Banach space of all continuous functions from J to \mathbb{R} with the norm

$$\| y \|_{\infty} = \sup\{| y(t) | : 0 \leq t \leq T\},$$

and let $L^1(J, \mathbb{R})$ denote the Banach space of functions $y : J \rightarrow \mathbb{R}$ that are Lebesgue integrable with norm

$$\| y \|_{L^1} = \int_0^T | y(t) | dt.$$

We let $L^\infty(J, \mathbb{R})$ be the Banach space of bounded measurable functions $y : J \rightarrow \mathbb{R}$ equipped with the norm

$$\| y \|_{L^\infty} = \inf \{c > 0 : | y(t) | \leq c, \quad \text{a . e . } t \in J\}.$$

Also, $AC^1(J, \mathbb{R})$ will denote the space of functions $y : J \rightarrow \mathbb{R}$ that are absolutely continuous and whose first derivative y' , is absolutely continuous. Let $(X, \|\cdot\|)$ be a Banach space and let $P_{cl}(X) = \{Y \in \mathcal{P}(X) : Y \text{ is closed}\}$, $P_b(X) = \{Y \in \mathcal{P}(X) : Y \text{ is bounded}\}$, $P_{cp}(X) = \{Y \in \mathcal{P}(X) : Y \text{ is compact}\}$, and $P_{cp,c}(X) = \{Y \in \mathcal{P}(X) : Y \text{ is compact and convex}\}$. A multivalued map $G : X \rightarrow P(X)$ is *convex* (*closed*) valued if $G(x)$ is convex (*closed*) for all $x \in X$. We say that G is *bounded on bounded sets* if $G(B) = \cup_{x \in B} G(x)$ is bounded in X for all $B \in P_b(X)$ (i . e . , $\sup_{x \in B} \{ \sup \{ \|y\| : y \in G(x) \} \} < \infty$). The mapping G is called *upper semi-continuous* (*u . s . c .*) on X if for each $x_0 \in X$, the set $G(x_0)$ is a nonempty closed subset of X , and if for each open set N of X containing $G(x_0)$, there exists an open neighborhood N_0 of x_0 such that $G(N_0) \subseteq N$. We say that G is *completely continuous* if $G(\mathcal{B})$ is relatively compact for every $\mathcal{B} \in P_b(X)$. If the multivalued map G is completely continuous with nonempty compact values, then G is *u . s . c .* if and only if G has a closed graph (i . e . , $x_n \rightarrow x_*$, $y_n \rightarrow y_*$, $y_n \in G(x_n)$ imply $y_* \in G(x_*)$). The mapping G has a *fixed point* if there is $x \in X$ such that $x \in G(x)$. The set of fixed points of the multivalued operator G will be denoted by $FixG$. A multivalued map $G : J \rightarrow P_{cl}(\mathbb{R})$ is said to be *measurable* if for every $y \in \mathbb{R}$, the function

$$t \mapsto d(y, G(t)) = \inf \{ \|y - z\| : z \in G(t) \}$$

is measurable. For more details on multivalued maps see the books of Aubin and Cellina [3], Aubin and Frankowska [4], Deimling [18], and Hu and Papageorgiou

[35].

Definition 2 . 1 . A multivalued map $F : J \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is Carath é odory if (i) $t \mapsto F(t, u)$ is measurable for each $u \in \mathbb{R}$, and

(i i) $u \mapsto F(t, u)$ is upper semicontinuous for almost all $t \in J$.

For each $y \in C(J, \mathbb{R})$, define the set of *selections* for F by

$$S_{F,y} = \{v \in L^1(J, \mathbb{R}) : v(t) \in F(t, y(t)) \text{ a.e. } t \in J\}.$$

Let (X, d) be a metric space induced from the normed space $(X, \|\cdot\|)$.

Consider

$$H_d : \mathcal{P}(X) \times \mathcal{P}(X) \rightarrow \mathbb{R}_+ \cup \{\infty\} \text{ given by } \\ H_d(A, B) = \max \{ \sup_{a \in A} d(a, B), \sup_{b \in B} d(A, b) \},$$

where $d(A, b) = \inf_{a \in A} d(a, b)$ and $d(a, B) = \inf_{b \in B} d(a, b)$. Then $(P_{b,cl}(X), H_d)$ is a metric space and $(P_{cl}(X), H_d)$ is a generalized metric space (see [39]).

Definition 2 . 2 . A multivalued operator $N : X \rightarrow P_{cl}(X)$ is called :

(a) γ -Lipschitz if there exists $\gamma > 0$ such that

$$H_d(N(x), N(y)) \leq \gamma d(x, y), \quad \text{for all } x, y \in X;$$

(b) a contraction if it is γ -Lipschitz with $\gamma < 1$.

The following lemma will be used in the sequel. **Lemma 2 . 3** ([16]). Let (X, d) be a complete metric space. If $N : X \rightarrow P_{cl}(X)$ is

a contraction, then $FixN \neq \emptyset$. **Definition 2 . 4** ([38 , 47]). The fractional (arbitrary) order integral of the function

$h \in L^1([a, b], \mathbb{R}_+)$ of order $\alpha \in \mathbb{R}_+$ is defined by

$$I_a^\alpha h(t) = \frac{1}{\Gamma(\alpha)} \int_a^t (t-s)^{\alpha-1} h(s) ds,$$

where Γ is the gamma function. When $a = 0$, we write $I^\alpha h(t) = h(t) * \varphi_\alpha(t)$, where $\varphi_\alpha(t) = \frac{t^{\alpha-1}}{\Gamma(\alpha)}$ for $t > 0$, $\varphi_\alpha(t) = 0$ for $t \leq 0$, and $\varphi_\alpha \rightarrow \delta(t)$ as $\alpha \rightarrow 0$, where δ is the delta function.

Definition 2.5 ([38, 47]). For a function h given on the interval $[a, b]$, the α -th Riemann - Liouville fractional - order derivative of h is defined by

$$(D_{a+}^\alpha h)(t) = \frac{1}{\Gamma(n-\alpha)} \left(\frac{d}{dt}\right)^n \int_a^t (t-s)^{n-\alpha-1} h(s) ds.$$

Here $n = [\alpha] + 1$ and $[\alpha]$ denotes the integer part of α . **Definition 2.6** ([38]). For a function h given on the interval $[a, b]$, the Caputo fractional - order derivative of h is defined by

$$({}^c D_{a+}^\alpha h)(t) = \frac{1}{\Gamma(n-\alpha)} \int_a^t (t-s)^{n-\alpha-1} h^{(n)}(s) ds,$$

where $n = [\alpha] + 1$.

3. THE CONVEX CASE

In this section, we are concerned with the existence of solutions for the problem (1.1) - (1.3) when the right hand side has convex values. Initially, we assume that F is a compact and convex valued multivalued map.

Definition 3.1. A function $y \in AC^1(J, \mathbb{R})$ is said to be a solution of (1.1) - (1.3), if there exists a function $v \in L^1(J, \mathbb{R})$ with $v(t) \in F(t, y(t))$, for a.e. $t \in J$, such that

$${}_c D^\alpha y(t) = v(t), \quad \text{a.e. } t \in J, \quad 1 < \alpha \leq 2,$$

and the function y satisfies conditions (1.2) and (1.3).

For the existence of solutions for the problem (1.1) - (1.3), we need the following auxiliary lemmas. **Lemma 3.2** ([53]). Let $\alpha > 0$; then the differential equation

$${}_c D^\alpha h(t) = 0$$

has the solutions $h(t) = c_0 + c_1 t + c_2 t^2 + \dots + c_{n-1} t^{n-1}$, where $c_i \in \mathbb{R}$, $i =$

$$0, 1, 2, \dots, n-1, \text{ and } n = [\alpha] + 1.$$

Lemma 3.3 ([53]). Let $\alpha > 0$; then

$$I^{\alpha^c} D^\alpha h(t) = h(t) + c_0 + c_1 t + c_2 t^2 + \dots + c_{n-1} t^{n-1}$$

for some $c_i \in \mathbb{R}$, $i = 0, 1, 2, \dots, n-1$, where $n = [\alpha] + 1$.

As a consequence of Lemmas 3.2 and 3.3, we have the following result which will

be useful in the remainder of the paper. **Lemma 3.4.** Let $1 < \alpha \leq 2$ and let $\sigma, \rho_1, \rho_2 : J \rightarrow \mathbb{R}$ be continuous. A function y is a solution of the fractional integral equation

$$y(t) = P(t) + \int_0^T G(t, s) \sigma(s) ds, \quad (3.1)$$

where

$$P(t) = \frac{T+1-t}{T+2} \int_0^T \rho_1(s) ds + \frac{t+1}{T+2} \int_0^T \rho_2(s) ds \quad (3.2)$$

and

$$G(t, s) = \text{braceleftmid} - \text{braceleftbt} - \frac{(t-s)^{\alpha-1}}{(1+t)^{\Gamma(\alpha)}} \frac{T_-^-}{2\Gamma(\alpha)} \frac{(s)_{(1+)}^{\alpha-1}}{T(1+t)^{\Gamma(\alpha)}} \frac{t(T-s)^{\alpha-1}}{T(1+t)^{\Gamma(\alpha)}} \frac{T_-^-}{\Gamma(\alpha-1)} \frac{(T_{(1+)}^s)^{\alpha-2}}{+2\Gamma(\alpha-1)} \frac{t(T-s)^{\alpha-2}}{+2\Gamma(\alpha-1)}, \quad (3.3)$$

if and only if y is a solution of the fractional BVP

$$c_D \alpha_y(t) = \sigma(t), \quad t \in J, \quad (3.4)$$

$$y(0) - y'(0) = \int_0^T \rho_1(s) ds, \quad (3.5)$$

$$y(T) + y'(T) = \int_0^T \rho_2(s) ds. \quad (3.6)$$

Proof. Assume that y satisfies (3.4); then Lemma 3.3 implies

$$y(t) = c_0 + c_1 t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \sigma(s) ds. \quad (3.7)$$

From (3.5) and (3.6), we obtain

$$c_0 - c_1 = \int_0^T \rho_1(s) ds \quad (3.8)$$

and

$$\begin{aligned} c_0 + c_1(T+1) + \frac{1}{\Gamma(\alpha)} \int_0^T (T-s)^{\alpha-1} \sigma(s) ds \\ + \frac{1}{\Gamma(\alpha-1)} \int_0^T (T-s)^{\alpha-2} \sigma(s) ds \\ = \int_0^T \rho_2(s) ds. \end{aligned} \quad (3.9)$$

Solving (3.8) – (3.9), we have

$$\begin{aligned} c_1 = \frac{1}{T+2} \int_0^T \rho_2(s) ds - \frac{1}{T+2} \int_0^T \rho_1(s) ds \\ - \frac{1}{(T+2)\Gamma(\alpha)} \int_0^T (T-s)^{\alpha-1} \sigma(s) ds \\ - \frac{1}{(T+2)\Gamma(\alpha-1)} \int_0^T (T-s)^{\alpha-2} \sigma(s) ds \end{aligned} \quad (3.10)$$

and

$$\begin{aligned}
c_0 = & \frac{T+1}{T+2} \int_0^T \rho_1(s) ds + \frac{1}{T+2} \int_0^T \rho_2(s) ds \\
& - \frac{1}{(T+2)\Gamma(\alpha)} \int_0^T (T-s)^{\alpha-1} \sigma(s) ds \\
& - \frac{1}{(T+2)\Gamma(\alpha-1)} \int_0^T (T-s)^{\alpha-2} \sigma(s) ds.
\end{aligned} \tag{3.11}$$

From (3 . 7) , (3 . 1 0) , (3 . 1 1) , and the fact that $\int_0^T = \int_0^t + \int_t^T$, we obtain (3 . 1) .

Conversely , if y satisfies equation (3 . 1) , then clearly (3 . 4) – (3 . 6) hold . \square

It is clear that the function $t \mapsto \int_0^T |G(t, s)| ds$ is continuous on J , and hence is bounded. Thus, we let

$$\tilde{G} := \sup \left\{ \int_0^T |G(t, s)| ds, t \in J \right\}.$$

Our first result is based on the nonlinear alternative of Leray - Schauder type for multivalued maps [32].

Theorem 3.6. *Assume that the following hypotheses hold :*

- (H1) $F : J \times \mathbb{R} \rightarrow \mathcal{P}_{cp,c}(\mathbb{R})$ is a Carathéodory multi-valued map ;
- (H2) There exist $p \in L^\infty(J, \mathbb{R}^+)$ and a continuous nondecreasing function $\psi :$

$$[0, \infty) \rightarrow (0, \infty) \text{ such that}$$

$\|F(t, u)\|_{\mathcal{P}} = \sup \{|v| : v \in F(t, u)\} \leq p(t)\psi(|u|)$ for all $t \in J, u \in \mathbb{R}$; (H3) There exist $\phi_g \in L^1(J, \mathbb{R}^+)$ and a continuous nondecreasing function $\psi^* :$

The proof will be given in

several steps.

EJDE - 2010 / 20 FRACTIONAL DIFFERENTIAL INCLUSIONS 7 **Step 1:** $N(y)$ is convex for each $y \in C(J, \mathbb{R})$. Indeed, if h_1 and h_2 belong to $N(y)$, then there exist $v_1, v_2 \in S_{F,y}$ such that, for all $t \in J$, we have

$$h_i(t) = P_y(t) + \int_0^T G(t, s)v_i(s)ds, \quad i = 1, 2.$$

Let $0 \leq d \leq 1$. Then, for each $t \in J$, we have

$$(dh_1 + (1-d)h_2)(t) = P_y(t) + \int_0^T G(t, s)[dv_1(s) + (1-d)v_2(s)]ds.$$

Since $S_{F,y}$ is convex (because F has convex values), we have $dh_1 + (1-d)h_2 \in N(y)$.

Step 2: N maps bounded sets into bounded sets in $C(J, \mathbb{R})$. Let $B_{\eta^*} = \{y \in C(J, \mathbb{R}) : \|y\|_{\infty} \leq \eta^*\}$ be a bounded set in $C(J, \mathbb{R})$ and let $y \in B_{\eta^*}$. Then for each $h \in N(y)$ and $t \in J$, from (H2) – (H4), we have

$$\begin{aligned} |h(t)| &\leq \frac{T+1}{T+2} \int_0^T |g(s, y(s))| ds + \frac{T+1}{T+2} \int_0^T |h(s, y(s))| ds \\ &\quad + \int_0^T |G(t, s)| |v(s)| ds \\ &\leq \frac{T+1}{T+2} \psi^*(\|y\|_{\infty}) \int_0^T \phi_g(s) ds + \frac{T+1}{T+2} \psi(\|y\|_{\infty}) \int_0^T \phi h(s) ds \\ &\quad + \psi(\|y\|_{\infty}) \|p\|_{L^{\infty}} \tilde{G}. \end{aligned}$$

Therefore,

$$\|h\|_{\infty} \leq \frac{T+1}{T+2} \psi^*(\eta^*) \int_0^T \phi_g(s) ds + \frac{T+1}{T+2} \psi^*(\eta^*) \int_0^T \phi h(s) ds + \psi(\eta^*) \|p\|_{L^{\infty}} \tilde{G} := \ell.$$

Step 3: N maps bounded sets into equicontinuous sets of $C(J, \mathbb{R})$. Let $t_1, t_2 \in J$ with $t_1 < t_2$, let B_{η^*} be a bounded set in $C(J, \mathbb{R})$ as in Step 2, and let $y \in B_{\eta^*}$ and

$$\begin{aligned} h &\in N(y). \text{ Then} \\ |h(t_2) - h(t_1)| &= \frac{t_2 - t_1}{T+2} \int_0^T |g(s, y(s))| ds + \frac{t_2 - t_1}{T+2} \int_0^T |h(s, y(s))| ds \\ &\quad + \int_0^T |G(t_2, s) - G(t_1, s)| |v(s)| ds \\ &\leq \frac{t_2 - t_1}{T+2} \psi^*(\eta^*) \int_0^T \phi_g(s) ds + \frac{t_2 - t_1}{T+2} \psi^*(\eta^*) \int_0^T \phi h(s) ds \\ &\quad + \psi(\eta^*) \|p\|_{L^{\infty}} \int_0^T |G(t_2, s) - G(t_1, s)| ds. \end{aligned}$$

As $t_1 \rightarrow t_2$, the right-hand side of the above inequality tends to zero. As a consequence of Steps 1 to 3 together with the Arzelà–Ascoli theorem, we can conclude that $N : C(J, \mathbb{R}) \rightarrow \mathcal{P}(C(J, \mathbb{R}))$ is completely continuous.

Step 4: N has a closed graph. Let $yn \rightarrow y^*$, $h_n \in N(yn)$, and $h_n \rightarrow h_*$. We need to show that $h_* \in N(y^*)$. Now, $h_n \in N(yn)$ implies there exists $v_n \in S_{F,yn}$ such that, for each $t \in J$,

$$h_n(t) = P_{yn}(t) + \int_0^T G(t, s)v_n(s)ds.$$

8 S . HAMANI , M . BENCHOHRA , J . R . GRAEF EJDE - 2 0 1 0 / 2 0 We must show that there exists $v_* \in S_{F,y*}$ such that for each $t \in J$,

$$h_*(t) = P_{y*}(t) + \int_0^T G(t,s)v_*(s)ds.$$

Since $F(t, \cdot)$ is upper semicontinuous , for every $\varepsilon > 0$, there exist $n_0(\varepsilon) \geq 0$ such that for every $n \geq n_0$, we have

$$v_n(t) \in F(t, yn(t)) \subset F(t, y*(t)) + \varepsilon B(0, 1) \quad \text{a.e. } t \in J.$$

Since $F(\cdot, \cdot)$ has compact values , there exists a subsequence $v_{n_m}(\cdot)$ such that

$$\begin{aligned} v_{n_m}(\cdot) &\rightarrow v_*(\cdot) \quad \text{as } m \rightarrow \infty, \\ v_*(t) &\in F(t, y*(t)) \quad \text{a.e. } t \in J. \end{aligned}$$

For every $w \in F(t, y*(t))$, we have

$$|v_{n_m}(t) - v_*(t)| \leq |v_{n_m}(t) - w| + |w - v_*(t)|,$$

and so

$$|v_{n_m}(t) - v_*(t)| \leq d(v_{n_m}(t), F(t, y*(t))).$$

By an analogous relation obtained by interchanging the roles of v_{n_m} and v_* , it follows that

$$|v_{n_m}(t) - v_*(t)| \leq H_d(F(t, yn(t)), F(t, y*(t))) \leq l(t) \|yn - y*\|_\infty.$$

Therefore ,

$$\begin{aligned} |h_{n_m}(t) - h_*(t)| &\leq \int_0^T |g(s, yn_m(s)) - g(s, y*(s))| ds \\ &\quad + \int_0^T |h(s, yn_m(s)) - h(s, y*(s))| ds \\ &\quad + \int_0^T G(t,s) |v_{n_m}(s) - v_*(s)| ds. \end{aligned}$$

Since

$$\begin{aligned} \int_0^T G(t,s) |v_{n_m}(s) - v_*(s)| ds &\leq \int_0^T G(t,s) l(s) ds \|yn_m - y*\|_\infty \\ &\leq \tilde{G} \|l\|_{L^\infty} \|yn_m - y*\|_\infty, \end{aligned}$$

and g and h are continuous , $\|h_{n_m} - h_*\|_\infty \rightarrow 0$ as $m \rightarrow \infty$.

Step 5 : *A priori bounds on solutions .* Let y be a possible solution of the problem

(1 . 1) – (1 . 3) . Then , there exists $v \in S_{F,y}$ such that , for each $t \in J$,

$$\begin{aligned} |y(t)| &\leq \frac{T+1}{T+2} \int_0^T \phi_g(s) \psi^*(|y(s)|) ds + \frac{T+1}{T+2} \int_0^T \phi h(s) \psi(|y(s)|) ds \\ &\quad + \int_0^T G(t,s) p(s) \psi(|y(s)|) ds \\ &\leq \frac{T+1}{T+2} \psi^*(\|y\|_\infty) \int_0^T \phi_g(s) ds + \frac{T+1}{T+2} \psi(\|y\|_\infty) \int_0^T \phi h(s) ds \\ &\quad + \psi(\|y\|_\infty) \tilde{G} \|p\|_{L^\infty}. \end{aligned}$$

$$\frac{\|y\|_\infty}{a\psi^*(\|y\|_\infty) + b\psi(\|y\|_\infty) + c\tilde{G}\psi(\|y\|_\infty)} \leq 1.$$

Hence , by (3 . 1 2) , there exists M such that $\|y\|_\infty \neq M$. Let

$$U = \{y \in C(J, \mathbb{R}) : \|y\|_\infty < M\}.$$

The operator $N : U \rightarrow \mathcal{P}(C(J, \mathbb{R}))$ is upper semicontinuous and completely continuous . From the choice of U , there is no $y \in \partial U$ such that $y \in \lambda N(y)$ for some $\lambda \in (0, 1)$. As a consequence of the nonlinear alternative of Leray - Schauder type ,

we conclude that N has a fixed point y in U which is a solution of the problem (1 . 1) - (1 . 3) . This completes the proof of the theorem . \square

4 . THE NONCONVEX CASE

This section is devoted to proving the existence of solutions for (1 . 1) - (1 . 3) with a nonconvex valued right hand side . Our first result is based on the fixed point theorem for contraction multivalued maps given by Covitz and Nadler [1 6] ; the second one makes use of a selection theorem due to Bressan and Colombo (see [1 4 , 27]) for lower semicontinuous operators with decomposable values combined with the nonlinear Leray - Schauder alternative .

Theorem 4 . 1 . Assume that (H 5) and the following hypotheses hold :

(H 7) There exists a constant $k^* > 0$ such that $|g(t, u) - g(t, u)| \leq k^* |u - u|$ for all $t \in J$ and $u, u \in \mathbb{R}$.

(H 8) There exists a constant $k^{**} > 0$ such that $|h(t, u) - h(t, u)| \leq k^{**} |u - u|$ for all $t \in J$ and $u, u \in \mathbb{R}$.

(H 9) $F : J \times \mathbb{R} \rightarrow P_{cp}(\mathbb{R})$ has the property that $F(\cdot, u) : J \rightarrow P_{cp}(\mathbb{R})$ is measurable , and integrably bounded for each $u \in \mathbb{R}$.

If

$$\left[\frac{T(T+1)}{T+2} k^* + \frac{T(T+1)}{T+2} k^{**} + k\tilde{G} \right] < 1, \quad (4.1)$$

where $k = \|l\|_{L^\infty}$, then (1 . 1) - (1 . 3) has at least one solution on J .

Remark 4 . 2 . For each $y \in C(J, \mathbb{R})$, the set $S_{F,y}$ is nonempty since , by (H 9), F has a measurable selection (see [1 5 , Theorem III . 6]) .

Proof of Theorem 4 . 1 . We shall show that N given in (3 . 1 3) satisfies the assumptions of Lemma 2 . 3 . The proof will be given in two steps .

Step 1 : $N(y) \in P_{cl}(C(J, \mathbb{R}))$ for all $y \in C(J, \mathbb{R})$. Let $(h_n)_n \geq 0 \in N(y)$ be such

that $h_n \rightarrow \tilde{h} \in C(J, \mathbb{R})$. Then there exists $v_n \in S_{F,y}$ such that , for each $t \in J$,

$$h_n(t) = P_y(t) + \int_0^T G(t, s) v_n(s) ds.$$

From (H 5) and the fact that F has compact values , we may pass to a subsequence if necessary to obtain that v_n converges weakly to v in $L_w^1(J, \mathbb{R})$ (the space endowed with the weak topology) . Using a standard argument , we can show that v_n converges strongly to v and hence $v \in S_{F,y}$. Thus , for each $t \in J$,

$$h_n(t) \rightarrow \tilde{h}(t) = P_y(t) + \int_0^T G(t,s)v(s)ds,$$

$$\text{so } \tilde{h} \in N(y).$$

Step 2 : *There exists $\gamma < 1$ such that*

$$H_d(N(y), N(\text{---}y)) \leq \gamma \|y - \text{---}y\|_\infty \quad \text{for all } y, \text{---}y \in C(J, \mathbb{R}).$$

Let $y, \text{---}y \in C(J, \mathbb{R})$ and $h_1 \in N(y)$. Then, there exists $v_1(t) \in F(t, y(t))$ such that,

for each $t \in J$,

$$h_1(t) = P_y(t) + \int_0^T G(t, s) v_1(s) ds.$$

From (H5) it follows that

$$H_d(F(t, y(t)), F(t, \text{---}y(t))) \leq l(t) \|y(t) - \text{---}y(t)\|.$$

Hence, there exists $w \in F(t, \text{---}y(t))$ such that

$$\|v_1(t) - w\| \leq l(t) \|y(t) - \text{---}y(t)\|, \quad t \in J.$$

Consider $U : J \rightarrow \mathcal{P}(\mathbb{R})$ given by

$$U(t) = \{w \in \mathbb{R} : \|v_1(t) - w\| \leq l(t) \|y(t) - \text{---}y(t)\|\}.$$

Since the multivalued operator $V(t) = U(t) \cap F(t, \text{---}y(t))$ is measurable (see Proposition [15, III.4]), there exists a function $v_2(t)$ which is a measurable selection for V . Thus, $v_2(t) \in F(t, \text{---}y(t))$, and for each $t \in J$,

$$\|v_1(t) - v_2(t)\| \leq l(t) \|y(t) - \text{---}y(t)\|.$$

For each $t \in J$, define

$$h_2(t) = P_{\text{---}y}(t) + \int_0^T G(t, s) v_2(s) ds,$$

where

$$P_{\text{---}y}(t) = \frac{T+1-t}{T+2} \int_0^T g(s, \text{---}y(s)) ds + \frac{t+1}{T+2} \int_0^T h(s, \text{---}y(s)) ds.$$

Then, for $t \in J$,

$$\begin{aligned} \|h_1(t) - h_2(t)\| &\leq \frac{T+1}{T+2} \int_0^T \|g(s, y(s)) - g(s, \text{---}y(s))\| ds \\ &\quad + \frac{T+1}{T+2} \int_0^T \|h(s, y(s)) - h(s, \text{---}y(s))\| ds \\ &\quad + \int_0^T G(s, t) \|v_1(s) - v_2(s)\| ds \\ &\leq \frac{T(T+1)}{T+2} k^* \|y - \text{---}y\|_\infty + \frac{T(T+1)}{T+2} k^{**} \|y - \text{---}y\|_\infty + \tilde{G} k \|y - \text{---}y\|_\infty \\ &\leq \left[\frac{T(T+1)}{T+2} k^* + \frac{T(T+1)}{T+2} k^{**} + k\tilde{G} \right] \|y - \text{---}y\|_\infty. \end{aligned}$$

Therefore ,

$$\| h_1 - h_2 \|_{\infty} \leq [\frac{T(T+1)}{T+2}k^* + \frac{T(T+1)}{T+2}k^{**} + k\tilde{G}] \| y - \text{---}y \|_{\infty}.$$

By an analogous relation , obtained by interchanging the roles of y and $-y$, it follows that

$$H_d(N(y), N(\text{---}y)) \leq [\frac{T(T+1)}{T+2}k^* + \frac{T(T+1)}{T+2}k^{**} + k\tilde{G}] \| y - \text{---}y \|_{\infty}.$$

Therefore, by (4.1), N is a contraction, and so by Lemma 2.3, N has a fixed point y that is a solution to (1.1) – (1.3). The proof is now complete. \square

Next, we present a result for problem (1.1) – (1.3) in the spirit of the nonlinear

alternative of Leray Schauder type [32] for single-valued maps combined with a selection theorem due to Bressan and Colombo [14] for lower semicontinuous multi-valued maps with decomposable values. Details on multivalued maps with decomposable values and their properties can be found in the recent book by Fryszkowski

[27].

Let A be a subset of $[0, T] \times \mathbb{R}$. We say that A is $\mathcal{L} \otimes \mathcal{B}$ measurable if A belongs to the σ -algebra generated by all sets of the form $\mathcal{J} \times D$ where \mathcal{J} is Lebesgue measurable in $[0, T]$ and D is Borel measurable in \mathbb{R} . A subset A of $L^1([0, T], \mathbb{R})$ is decomposable if for all $u, v \in A$ and measurable $\mathcal{J} \subset [0, T]$, $u\chi_{\mathcal{J}} + v\chi_{[0, T] - \mathcal{J}} \in A$, where χ stands for the characteristic function.

Let $G : X \rightarrow \mathcal{P}(X)$ be a multivalued operator with nonempty closed values. We say that G is lower semi-continuous (l.s.c.) if the set $\{x \in X : G(x) \cap B \neq \emptyset\}$ is open for any open set B in X .

Definition 4.3. Let Y be a separable metric space and $N : Y \rightarrow \mathcal{P}(L^1([0, T], \mathbb{R}))$ be a multivalued operator. We say N has property (BC) if

- (1) N is lower semi-continuous (l.s.c.);
- (2) N has nonempty closed and decomposable values.

Let $F : [0, T] \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ be a multivalued map with nonempty compact values. Assign to F the multivalued operator $\mathcal{F} : C([0, T], \mathbb{R}) \rightarrow \mathcal{P}(L^1([0, T], \mathbb{R}))$ by

$$\mathcal{F}(y) = \{w \in L^1([0, T], \mathbb{R}) : w(t) \in F(t, y(t)) \text{ for a.e. } t \in [0, T]\}.$$

The operator \mathcal{F} is called the Niemytzki operator associated to F .

Definition 4.4. Let $F : [0, T] \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ be a multivalued function with nonempty compact values. We say F is of lower semi-continuous type (l.s.c. type) if its associated Niemytzki operator \mathcal{F} is lower semi-continuous and has nonempty closed and decomposable values.

Next, we state a selection theorem due to Bressan and Colombo.

Theorem 4.5 ([14]). Let Y be a separable metric space and $N : Y \rightarrow \mathcal{P}(L^1([0, T], \mathbb{R}))$ be a multivalued operator that has property (BC). Then N has a continuous selection, i.e., there exists a continuous (single-valued) function $\tilde{g} : Y \rightarrow L^1([0, T], \mathbb{R})$ such that $\tilde{g}(y) \in N(y)$ for every $y \in Y$.

Let us introduce the hypotheses

(H10) $F : [0, T] \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is a nonempty compact valued multivalued map such

that :

(a) $(t, u) \mapsto F(t, u)$ is $\mathcal{L} \otimes \mathcal{B}$ measurable;

(b) $y \mapsto F(t, y)$ is lower semi-continuous for a.e. $t \in [0, T]$;

(H11) for each $q > 0$, there exists a function $h_q \in L^1([0, T], \mathbb{R}^+)$ such that $\|F(t, y)\|_{\mathcal{P}} \leq h_q(t)$ for a.e. $t \in [0, T]$ and for $y \in \mathbb{R}$ with $|y| \leq q$.

The following lemma is crucial in the proof of our main theorem.

Lemma 4.6 ([26]). Let $F : [0, T] \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ be a multivalued map with nonempty compact values. Assume that (H10), (H11) hold. Then F is of lower semicontinuous

type .

We are now ready for our next main result in this section.

Theorem 4.7. *Suppose that conditions (H2) – (H4), (H6), (H10), (H11) are satisfied. Then the problem (1.1) – (1.3) has at least one solution.*

Proof. Conditions (H10) and (H11) imply, by Lemma 4.6, that F is of lower semi-continuous type. By Theorem 4.5, there exists a continuous function $f : C([0, T], \mathbb{R}) \rightarrow L^1([0, T], \mathbb{R})$ such that $f(y) \in \mathcal{F}(y)$ for all $y \in C([0, T], \mathbb{R})$. Consider the problem :

$${}_D c_D \alpha_y(t) = f(y)(t), \quad \text{for a.e. } t \in J = [0, T], \quad 1 < \alpha \leq 2, \quad (4.2)$$

$$y(0) - y'(0) = \int_0^T g(s, y) ds, \quad (4.3)$$

$$y(0) - y'(0) = \int_0^T g(s, y) ds. \quad (4.4)$$

Observe that if $y \in AC^1([0, T], \mathbb{R})$ is a solution of the problem (4.2) – (4.4), then y is a solution to the problem (1.1) – (1.3).

We reformulate the problem (4.2) – (4.4) as a fixed point problem for the operator

$N_1 : C([0, T], \mathbb{R}) \rightarrow C([0, T], \mathbb{R})$ defined by :

$$N_1(y)(t) = P_y(t) + \int_0^T G(t, s) f(y)(s) ds,$$

where the functions P_y and G are given by (3.14) and (3.3), respectively. Using (H2) – (H4) and (H6), we can easily show (using arguments similar to those in the proof of Theorem 3.6) that the operator N_1 satisfies all conditions in the Leray-Schauder alternative. \square

5. TOPOLOGICAL STRUCTURE OF THE SOLUTIONS SET

In this section, we present a result on the topological structure of the set of solutions of (1.1) – (1.3).

Theorem 5.1. *Assume that (H1) and the following hypotheses hold :*

(H12) *There exists $p \in C(J, \mathbb{R}^+)$ such that $\|F(t, u)\|_{\mathcal{P}} \leq p(t)(|u| + 1)$ for all $t \in J$*

$$\text{and } u \in \mathbb{R};$$

(H13) *There exists $p_1 \in C(J, \mathbb{R}^+)$ such that $|g(t, u)| \leq p_1(t)(|u| + 1)$ for all $t \in J$*

$$\text{and } u \in \mathbb{R};$$

(H14) *There exists $p_2 \in C(J, \mathbb{R}^+)$ such that $|h(t, u)| \leq p_2(t)(|u| + 1)$ for all $t \in J$*

$$\text{and } u \in \mathbb{R}.$$

If

$$\frac{T(T+1)}{T+2} \frac{M+1}{M} [\|p_1\|_{\infty} + \|p_2\|_{\infty} + \tilde{G} \frac{T+2}{T(T+1)} \|p\|_{L^{\infty}}] < 1,$$

then the solution set of (1.1) – (1.3) is nonempty and compact in $C(J, \mathbb{R})$.

Proof. Let

$S = \{y \in C(J, \mathbb{R}) : y \text{ is solution of (1.1) – (1.3)}\}$. From Theorem 3.6, $S \neq \emptyset$.

Now, we prove that S is compact. Let $(y_n)_n \in S$;

then there exists $v_n \in S_{F, y_n}$ such that, for $t \in J$,

$$y_n(t) = P_{y_n}(t) + \int_0^T G(t, s)v_n(s)ds,$$

$$P_{yn}(t) = \frac{T+1-t}{T+2} \int_0^T g(s, yn(s))ds + \frac{t+1}{T+2} \int_0^T h(s, yn(s))ds$$

and the function $G(t, s)$ is given by (3.3).

From (H12) – (H14) we can prove that there exists a constant $M_1 > 0$ such that

$$\| yn \|_{\infty} \leq M_1 \quad \text{for all } n \geq 1.$$

As in Step 3 of the proof of Theorem 3.6, we can easily show that the set $\{yn : n \geq 1\}$ is equicontinuous in $C(J, \mathbb{R})$, and so by the Arz é la - Ascoli Theorem, we can conclude that there exists a subsequence (denoted again by $\{yn\}$) of $\{yn\}$ converging to y in $C(J, \mathbb{R})$. We shall show that there exist $v(\cdot) \in F(\cdot, y(\cdot))$ such that

$$y(t) = P_y(t) + \int_0^T G(t, s)v(s)ds.$$

Since $F(t, \cdot)$ is upper semicontinuous, for every $\varepsilon > 0$, there exists $n_0(\varepsilon) \geq 0$ such that, for every $n \geq n_0$, we have

$$v_n(t) \in F(t, yn(t)) \subset F(t, y(t)) + \varepsilon B(0, 1) \quad \text{a.e. } t \in J.$$

Since $F(\cdot, \cdot)$ has compact values, there exists a subsequence $v_{n_m}(\cdot)$ such that

$$\begin{aligned} v_{n_m}(\cdot) &\rightarrow v(\cdot) \quad \text{as } m \rightarrow \infty, \\ v(t) &\in F(t, y(t)) \quad \text{a.e. } t \in J. \end{aligned}$$

It is clear that the subsequence $v_{n_m}(t)$ is integrally bounded. By the Lebesgue dominated convergence theorem, we have that $v \in L^1(J, \mathbb{R})$, which implies that

$$v \in S_{F,y}. \text{ Thus,}$$

$$y(t) = P_y(t) + \int_0^T G(t, s)v(s)ds, \quad t \in J.$$

Hence, $S \in \mathcal{P}_{cp}(C(J, \mathbb{R}))$, and this completes the proof of the theorem. \square

6. AN EXAMPLE

As an application of the main results, we consider the fractional differential inclusion

$${}_CD^\alpha y(t) \in F(t, y), \quad \text{a.e. } t \in J = [0, 1], \quad 1 < \alpha \leq 2, \quad (6.1)$$

$$y(0) - y'(0) = \int_0^1 s^5(1 + |y(s)|)ds, \quad (6.2)$$

$$y(1) + y'(1) = \int_0^1 s^5(1 + |y(s)|)ds. \quad (6.3)$$

Set

$$F(t, y) = \{v \in \mathbb{R} : f_1(t, y) \leq v \leq f_2(t, y)\},$$

where $f_1, f_2 : J \times \mathbb{R} \rightarrow \mathbb{R}$ are measurable in t and Lipschitz continuous in y . We assume that for each $t \in J$, $f_1(t, \cdot)$ is lower semi - continuous (i.e., the set $\{y \in \mathbb{R} : f_1(t, y) > \mu\}$ is open for all $\mu \in \mathbb{R}$), and assume that for each $t \in J$, $f_2(t, \cdot)$ is upper semi - continuous (i.e., the set $\{y \in \mathbb{R} : f_2(t, y) < \mu\}$ is open for each μ). Assume that

$$\max(|f_1(t, y)|, |f_2(t, y)|) \leq \frac{t}{9}(1 + |y|) \quad \text{for all } t \in J \text{ and } y \in \mathbb{R}.$$

$$G(t, s) = \frac{(t-s)^{\alpha-1}}{(1+t)^{3\Gamma(\alpha)}} \frac{1-(s)^{\alpha-1}}{(1+)^{(\alpha)}} \frac{t(1-s)^{\alpha-1}}{(1+t)^{3\Gamma(\alpha)}} \frac{1-(s)^{\alpha-2}}{(1+)^{(\alpha-1)}} \frac{t(1-s)^{\alpha-2}}{3\Gamma(\alpha-1)} \quad 0 \leq t \leq s \leq 1$$

We have $T = 1, \phi_g(t) = t^5, \phi_h(t) = t^5, a = 1/9, b = 1/9, c = 1/9$, and

$$\psi(y) = 1 + y, \quad \psi^*(y) = 1 + y, \quad -\psi(y) = 1 + y, \quad \text{for all } y \in [0, \infty).$$

Also ,

$$\begin{aligned} \int_0^1 G(t, s) ds &= \int_0^t G(t, s) ds + \int_t^1 G(t, s) ds \\ &= \frac{t^\alpha}{\Gamma(\alpha+1)} + \frac{(1+t)(1-t)^\alpha}{3\Gamma(\alpha+1)} - \frac{(1+t)}{3\Gamma(\alpha+1)} + \frac{(1+t)(1-t)^{\alpha-1}}{3\Gamma(\alpha)} \\ &\quad - \frac{(1+t)(1-t)^\alpha}{3\Gamma(\alpha)} + \frac{(1+t)(1-t)^{\alpha-1}}{3\Gamma(\alpha)} \end{aligned}$$

It is easy to see that

$$\tilde{G} < \frac{3}{\Gamma(\alpha+1)} + \frac{2}{\Gamma(\alpha)} < 5.$$

A simple calculation shows that condition (3 . 1 2) is satisfied for $M > 7/2$. It is clear that F is compact and convex valued , and it is upper semi - continuous (see [1 8]) . Since all the conditions of Theorem 3 . 6 are satisfied , BVP (6 . 1) - (6 . 3) has at least one solution y on J .

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