Int. J. Open Problems Compt. Math., Vol. 11, No. 4, December 2018 ISSN 1998-6262; Copyright ©ICSRS Publication, 2018 www.i-csrs.org

# An Application of Banach Contraction Principle for a Class of Fractional HDEs

#### Soumia FERRAOUN, Zoubir DAHMANI

Laboratory LPAM, Faculty of SEI, University of Mostaganem, Algeria

e-mail: soumia.ferraoun@gmail.com e-mail: zzdahmani@yahoo.fr

Communicated by: Benharrat Belaidi

#### Abstract

This paper deals with a class of fractional hybrid differential equations. We prove an integral representation for the studied class. Then, using the Banach contraction principle, we establish some conditions that guarantee for us the existence of a unique solution.

**Keywords:** Hybrid differential equation, Caputo derivative, Fixed point, Existence and uniqueness of solution.

2010 Mathematics Subject Classification: 34A38, 32A65, 26A33.

## 1 Introduction

The theory of Fractional differential equations is a very important tool for modeling phenomena in applied sciences and engineering. It has applications in physics, biology, chemistry, engineering, and more others applied domains, we refer the reader to [9], [3], [13], [14].

On the other hand, the hybrid differential equations is very interesting domain for mathematics and physics, see for instance [1], [2], [5], [7], [8].

In this paper, we are concerned with the following problem:

$$\begin{cases} \mathbf{D}^{\alpha_{1}} \left( \frac{x_{1}(t)}{f_{1}(t,x_{1}(t),x_{2}(t),...,x_{n}(t))} \right) &= h_{1}(t,x_{1}(t),x_{2}(t),...,x_{n}(t)) \\ &+ I^{\delta_{1}}k_{1}(t,x_{1}(t),x_{2}(t),...,x_{n}(t)), t \in J \\ \mathbf{D}^{\alpha_{2}} \left( \frac{x_{(}t)}{f_{2}(t,x_{1}(t),x_{2}(t),...,x_{n}(t))} \right) &= h_{2}(t,x_{1}(t),x_{2}(t),...,x_{n}(t)) \\ &+ I^{\delta_{2}}k_{2}(t,x_{1}(t),x_{2}(t),...,x_{n}(t)), t \in J \\ &\dots \\ \mathbf{D}^{\alpha_{n}} \left( \frac{x_{n}(t)}{f_{n}(t,x_{1}(t),x_{2}(t),...,x_{n}(t))} \right) &= h_{n}(t,x_{1}(t),x_{2}(t),...,x_{n}(t)) \\ &+ I^{\delta_{n}}k_{n}(t,x_{1}(t),x_{2}(t),...,x_{n}(t)), t \in J \\ &\dots \\ x_{i}(0) &= \theta_{i} \int_{0}^{\beta_{i}} \varphi_{i}(s)x_{i}(s)ds, \\ &0 < \beta_{i} < 1, i = 1, 2, ..., n. \end{cases}$$

$$(1)$$

where, for i = 1, ..., n, the symbols  $D^{\alpha_i}$  denote the Caputo fractional derivative with  $0 < \alpha_i < 1$ , the symbols  $I^{\delta_i}$  denote the Riemann-Liouville fractional integral of order  $\delta_i$  with  $0 < \delta_i < 1$ . J = [0, 1] represent a time interval,  $\theta_i$  are real numbers,  $\varphi_i$  are continuous functions on  $[0, \beta_i]$ ,  $f_i \in C((J \times \mathbb{R}^n, \mathbb{R} - \{0\}))$ and  $h_i, k_i \in C((J \times \mathbb{R}^n, \mathbb{R})$ .

The paper is organized as follow: Section 2 is devoted to the preliminaries and most important notions used throughout the development of the main results. In section 3, we prove the main result on the uniqueness of one solution for the hybrid problem. In the last section, two open questions are posed.

## 2 Preliminaries

We introduce some useful definitions and lemmas [6, 10, 11, 12].

**Definition 2.1** Let  $\alpha > 0$  and  $h : [a, b] \mapsto \mathbb{R}$  be a continuous function. The Riemann-Liouville integral of order  $\alpha$  is defined by:

$$I_a^{\alpha}h(t) = \frac{1}{\Gamma(\alpha)} \int_a^t (t-s)^{\alpha-1}h(s)ds, \alpha > 0, a \le t \le b.$$

Fractional hybrid differential equations...

**Definition 2.2** Let  $\alpha > 0, n - 1 < \alpha \leq n$  and  $h \in C^n([0,T], \mathbb{R})$ . The Caputo fractional derivative is defined by:

$$D^{\alpha}h(t) = I^{n-\alpha}\frac{d^n}{dt^n}(h(t))$$
$$= \frac{1}{\Gamma(n-\alpha)}\int_0^t (t-s)^{n-\alpha-1}h^{(n)}(s)ds.$$

**Lemma 2.3** For  $n - 1 < \alpha \leq n$  and  $h \in C^n([0, T], \mathbb{R})$ , the equation  $D^{\alpha}h = 0$  has a general solution given by:

$$h(t) = c_0 + c_1 t + c_2 t^2 + \dots + c_{n-1} t^{n-1},$$

where  $c_i \in \mathbb{R}, i = 0, 1, 2, ..., n - 1$ .

Lemma 2.4 Under the assumptions of the above lemma, we have

$$I^{\alpha}D^{\alpha}h(t) = h(t) + c_0 + c_1t + c_2t^2 + \dots + c_{n-1}t^{n-1}.$$

## 3 Main Results

First, we mention that we have noted  $x = (x_1, x_2, ..., x_n)$  and  $x(t) = (x_1(t), x_2(t), ..., x_n(t))$  for the clarity of calculations and reading.

The following lemma is an auxiliary result that will be used throughout this paper. We prove:

**Lemma 3.1** Let i = 1, 2, ..., n and  $0 < \alpha_i, \delta_i < 1$ . If  $f_i \in C((J \times \mathbb{R}^n, \mathbb{R} - \{0\}))$ and  $h_i, k_i \in C((J \times \mathbb{R}^n, \mathbb{R}), then, the solution of the equation$ 

$$D^{\alpha_i}\left(\frac{x_i(t)}{f_i(t,x(t))}\right) = h_i(t,x(t)) + I^{\delta_i}k_i(t,x(t))$$
(2)

under the condition:

$$x_i(0) = \theta_i \int_0^{\beta_i} \varphi_i(s) x_i(s) ds, 0 < \beta_i < 1, i = 1, 2, ..., n$$
(3)

is given by:

$$\begin{aligned} x_i(t) &= f_i(t, x(t)) \left( \frac{1}{\Gamma(\alpha_i)} \int_0^t (t - \tau)^{\alpha_i - 1} h_i(\tau, x(\tau)) d\tau \\ &+ \frac{1}{\Gamma(\alpha_i + \delta_i)} \int_0^t (t - \tau)^{\alpha_i + \delta_i - 1} k_i(\tau, x(\tau)) d\tau \\ &+ \frac{\theta_i}{f_i(0, x(0)) - \theta_i \int_0^{\beta_i} f_i(s, x(s)) \varphi_i(s) ds} \int_0^{\beta_i} f_i(s, x(s)) \varphi_i(s) \\ &\times \left[ \frac{1}{\Gamma(\alpha_i)} \int_0^t (t - \tau)^{\alpha_i - 1} h_i(\tau, x(\tau)) d\tau \\ &+ \frac{1}{\Gamma(\alpha_i + \delta_i)} \int_0^t (t - \tau)^{\alpha_i + \delta_i - 1} k_i(\tau, x(\tau)) d\tau \right] ds \end{aligned}$$
(4)

with:  $f_i(0, x(0)) \neq \theta_i \int_0^{\beta_i} f_i(s, x(s))\varphi_i(s)ds.$ 

### $\mathbf{Proof}$

For i = 1, ..., n, we consider:

$$D^{\alpha_i}\left(\frac{x_i(t)}{f_i(t,x(t))}\right) = h_i(t,x(t)) + I^{\delta_i}k_i(t,x(t)), t \in J$$
(5)

By using lemmas 2.3 and 2.4, the general solution of (5) is given by:

$$\frac{x_i(t)}{f_i(t,x(t))} = I^{\alpha_i} h_i(t,x(t)) + I^{\alpha_i + \delta_i} k_i(t,x(t)) - c_0$$
(6)

where  $c_0 \in \mathbb{R}$  is an arbitrary constant.

From (6), we get:

$$x_i(t) = f_i(t, x(t))[I^{\alpha_i}h_i(t, x(t)) + I^{\alpha_i + \delta_i}k_i(t, x(t)) - c_0]$$
(7)

On the other hand, we multiply both sides of (7) by  $\theta_i \varphi_i(s)$ , we get:

$$\theta_i \varphi_i(s) x_i(s) = \theta_i \varphi_i(s) f_i(s, x(s)) \\ \times [I^{\alpha_i} h_i(s, x(s) + I^{\alpha_i + \delta_i} k_i(s, x(s))] - c_0 \theta_i f_i(s, x(s)) \varphi_i(s)$$
(8)

Then thanks to (8), we can write:

$$\theta_i \int_0^{\beta_i} \varphi_i(s) x_i(s) ds = \theta_i \int_0^{\beta_i} \varphi_i(s) f_i(s, x(s)) [I^{\alpha_i} h_i(s, x(s) + I^{\alpha_i + \delta_i} k_i(s, x(s))] ds$$
$$-c_0 \int_0^{\beta_i} \theta_i f_i(s, x(s)) \varphi_i(s) ds$$
(9)

Using (3) and (7), we get:

$$c_0\left(f_i(0,x(0)) - \int_0^{\beta_i} \theta_i f_i(s,x(s))\varphi_i(s)ds\right) = \theta_i \int_0^{\beta_i} \varphi_i(s)f_i(s,x(s)) \times [I^{\alpha_i}h_i(s,x(s) + I^{\alpha_i + \delta_i}k_i(s,x(s))]ds$$

$$\times [I^{\alpha_i}h_i(s,x(s) + I^{\alpha_i + \delta_i}k_i(s,x(s))]ds$$
(10)

which becomes

$$c_{0} = \frac{\theta_{i}}{\left(f_{i}(0, x(0)) - \int_{0}^{\beta_{i}} \theta_{i} f_{i}(s, x(s))\varphi_{i}(s)ds\right)}$$

$$\int_{0}^{\beta_{i}} \varphi_{i}(s)f_{i}(s, x(s))[I^{\alpha_{i}}h_{i}(s, x(s) + I^{\alpha_{i}+\delta_{i}}k_{i}(s, x(s))]ds$$

$$(11)$$

Replacing  $c_0$  by its value in (7), we obtain (4).

Now, we introduce the following Banach spaces:

$$X_i = \{x_i(t), i = 1, ..., n : x_i \in C(J, \mathbb{R})\}$$
(12)

with the norm:

$$||x_i||_{X_i} = \sup\{|x_i(t)| : t \in J\}$$
(13)

where i = 1.., n.

We bring to the attention that for  $i = 1, 2, ..., n, (X_i, ||.||_{X_i})$  is a Banach space.

The product space:

$$\left(\prod_{i=1}^{n} X_{i}, \|.\|_{\prod_{i=1}^{n} X_{i}}\right)$$
(14)

is also a Banach space.

Let  $\mathcal{Q}$  be an operator defined by:

$$\mathcal{Q}: \qquad \prod_{i=1}^{n} X_i \to \prod_{i=1}^{n} X_i$$
$$x(t) \longmapsto \mathcal{Q}x(t)$$

S. Ferraoun and Z. Dahmani

such that for  $t \in J$ ,

$$\mathcal{Q}x(t) = \left(\mathcal{Q}_1 x(t), \mathcal{Q}_2 x(t), ..., \mathcal{Q}_n x(t)\right)$$
(15)

where:

$$\begin{aligned} \mathcal{Q}_{i}x(t) &= f_{i}(t,x(t)) \left( \frac{1}{\Gamma(\alpha_{i})} \int_{0}^{t} (t-\tau)^{\alpha_{i}-1} h_{i}(\tau,x(\tau)) d\tau \right. \\ &+ \frac{1}{\Gamma(\alpha_{i}+\delta_{i})} \int_{0}^{t} (t-\tau)^{\alpha_{i}+\delta_{i}-1} k_{i}(\tau,x(\tau)) d\tau \\ &+ \frac{\theta_{i}}{f_{i}(0,x(0)) - \theta_{i} \int_{0}^{\beta_{i}} f_{i}(s,x(s)) \varphi_{i}(s) ds} \int_{0}^{\beta_{i}} f_{i}(s,x(s)) \varphi_{i}(s) \\ &\times \left[ \frac{1}{\Gamma(\alpha_{i})} \int_{0}^{t} (t-\tau)^{\alpha_{i}-1} h_{i}(\tau,x(\tau)) d\tau \right. \\ &+ \frac{1}{\Gamma(\alpha_{i}+\delta_{i})} \int_{0}^{t} (t-\tau)^{\alpha_{i}+\delta_{i}-1} k_{i}(\tau,x(\tau)) d\tau \right] ds \end{aligned}$$

$$(16)$$

#### **Theorem 3.2** We suppose that:

**H**1. There exist constants  $\xi_{ij}$ ,  $\zeta_{ij}$  for i, j = 1, ..., n such that:

$$|h_i(t, x_1, ..., x_n) - h_i(t, y_1, ..., y_n)| \le \sum_{j=1}^n \xi_{ij} |x_j - y_j|$$
(17)

and

$$|k_i(t, x_1, ..., x_n) - k_i(t, y_1, ..., y_n)| \le \sum_{j=1}^n \zeta_{ij} |x_j - y_j|$$
(18)

for all  $t \in J, x, y \in \mathbb{R}^n$ .

**H2.** There exist nonnegative constants  $F_i$ , i = 1, ..., n such that for all  $t \in J$  and  $x \in \mathbb{R}_n |f_i(t, x(t))| \leq F_i$ .

Fractional hybrid differential equations...

$$\begin{aligned} \mathbf{H3.} \ &\sum_{i=1}^{n} \left( \Phi_{i} \sum_{j=1}^{n} \xi_{ij} + \Psi_{i} \sum_{j=1}^{n} \zeta_{ij} \right) < 1, \ where: \\ \\ &\Phi_{i} \ := \ \frac{F_{i}}{\Gamma(\alpha_{i}+1)} + \frac{F_{i}^{2} |\theta_{i}| \sup_{s \in J} |\varphi_{i}(s)| \beta_{i}^{\alpha_{i}+1}}{\Gamma(\alpha_{i}+2) |f_{i}(0, x(0)) - \theta_{i} \int_{0}^{\beta_{i}} f_{i}(s, x(s)) \varphi_{i}(s) ds|} \\ \\ &\Psi_{i} \ := \ \frac{F_{i}}{\Gamma(\alpha_{i}+\delta_{i}+1)} + \frac{F_{i}^{2} |\theta_{i}| \sup_{s \in J} |\varphi_{i}(s)| \beta_{i}^{\alpha_{i}+\delta_{i}+1}}{\Gamma(\alpha_{i}+\delta_{i}+2) |f_{i}(0, x(0)) - \theta_{i} \int_{0}^{\beta_{i}} f_{i}(s, x(s)) \varphi_{i}(s) ds|} \end{aligned}$$

are satisfied.

Then, there exists a unique solution to (1) provided that  $\theta_i$  and  $f_i(0, x(0))$  satisfy the condition of Lemma 3.1.

#### Proof

We need to proceed on two steps: **Step 1:** Let  $\mathfrak{B}_r$  be given by  $\mathfrak{B}_r = \{x \in \prod_{i=1}^n X_i : ||x||_{\prod_{i=1}^n X_i} < r\}$  where r is defined by:

$$r \ge \frac{\sum_{i=1}^{n} \Phi_i H_i + \Psi_i K_i}{1 - \sum_{i=1}^{n} (\Phi_i \sum_{j=1}^{n} \xi_{ij} + \Psi_i \sum_{j=1}^{n} \zeta_{ij})}$$
(19)

Let  $H_i := \sup_{t \in J} |h_i(t, 0, ...0)| < \infty$  and  $K_i := \sup_{t \in J} t \in J |k_i(t, 0, ...0)| < \infty$ , for i = 1, ..., n.

We notice that using (H1), for  $x \in \mathfrak{B}_r$ , we can write:

$$|h_{i}(t, x_{1}, ..., x_{n})| \leq |h_{i}(t, x_{1}, ..., x_{n}) - h_{i}(t, 0, ...0)| + |h_{i}(t, 0, ...0)| \leq \sum_{j=1}^{n} \xi_{ij}j|x_{j}| + H_{i} \leq \sum_{j=1}^{n} \xi_{ij}r + H_{i}$$
(20)

and

$$\begin{aligned} |k_i(t, x_1, ..., x_n)| &\leq |k_i(t, x_1, ..., x_n) - k_i(t, 0, ...0)| + |k_i(t, 0, ...0)| \\ &\leq \sum_{j=1}^n \zeta_{ij} |x_j| + K_i \\ &\leq \sum_{j=1}^n \zeta_{ij} r + K_i \end{aligned}$$
(21)

On the other hand, we have:

$$\begin{aligned} |\mathcal{Q}_{i}x(t)| &\leq |f_{i}(t,x(t))| \left(\frac{1}{\Gamma(\alpha_{i})} \int_{0}^{t} (t-\tau)^{\alpha_{i}-1} |h_{i}(\tau,x(\tau))| d\tau \right. \\ &+ \frac{1}{\Gamma(\alpha_{i}+\delta_{i})} \int_{0}^{t} (t-\tau)^{\alpha_{i}+\delta_{i}-1} |k_{i}(\tau,x(\tau))| d\tau \\ &+ \frac{|\theta_{i}|}{|f_{i}(0,x(0)) - \theta_{i} \int_{0}^{\beta_{i}} f_{i}(s,x(s))\varphi_{i}(s)ds|} \int_{0}^{\beta_{i}} |f_{i}(s,x(s))| |\varphi_{i}(s)| \\ &\times \left[\frac{1}{\Gamma(\alpha_{i})} \int_{0}^{t} (t-\tau)^{\alpha_{i}-1} |h_{i}(\tau,x(\tau))| d\tau \right. \\ &+ \frac{1}{\Gamma(\alpha_{i}+\delta_{i})} \int_{0}^{t} (t-\tau)^{\alpha_{i}+\delta_{i}-1} |k_{i}(\tau,x(\tau))| d\tau \right] ds \end{aligned}$$

$$(22)$$

So, using  $(\mathbf{H}1)$ ,  $(\mathbf{H}2)$ , (20), and (21), we get:

$$\begin{aligned} |\mathcal{Q}_{i}x(t)| &\leq F_{i}\left(\frac{1}{\Gamma(\alpha_{i})}\int_{0}^{t}(t-\tau)^{\alpha_{i}-1}d\tau\left(\sum_{j=1}^{n}\xi_{ij}r+H_{i}\right)\right) \\ &+\frac{1}{\Gamma(\alpha_{i}+\delta_{i})}\int_{0}^{t}(t-\tau)^{\alpha_{i}+\delta_{i}-1}d\tau\left(\sum_{j=1}^{n}\zeta_{ij}r+K_{i}\right) \\ &+\frac{F_{i}|\theta_{i}|\sup_{s\in J}|\varphi_{i}(s)|}{|f_{i}(0,x(0))-\theta_{i}\int_{0}^{\beta_{i}}f_{i}(s,x(s))\varphi_{i}(s)ds|} \\ &\times\int_{0}^{\beta_{i}}\left[\frac{1}{\Gamma(\alpha_{i})}\int_{0}^{t}(t-\tau)^{\alpha_{i}-1}d\tau\left(\sum_{j=1}^{n}\xi_{ij}r+H_{i}\right)\right. \end{aligned}$$
(23)
$$\\ &+\frac{1}{\Gamma(\alpha_{i}+\delta_{i})}\int_{0}^{t}(t-\tau)^{\alpha_{i}+\delta_{i}-1}d\tau\left(\sum_{j=1}^{n}\zeta_{ij}r+K_{i}\right)\right]ds \end{aligned}$$

which leads to:

$$\begin{aligned} \|\mathcal{Q}_{i}x\|_{X_{i}} &\leq \left(\frac{F_{i}}{\Gamma(\alpha_{i}+1)} + \frac{F_{i}^{2}|\theta_{i}|\sup_{s\in J}|\varphi_{i}(s)|\beta_{i}^{\alpha_{i}+1}}{\Gamma(\alpha_{i}+2)|f_{i}(0,x(0)) - \theta_{i}\int_{0}^{\beta_{i}}f_{i}(s,x(s))\varphi_{i}(s)ds|}\right) \left(\sum_{j=1}^{n}\xi_{ij}r + H_{i}\right) \\ &+ \left(\frac{F_{i}}{\Gamma(\alpha_{i}+\delta_{i}+1)} + \frac{F_{i}^{2}|\theta_{i}|\sup_{s\in J}|\varphi_{i}(s)|\beta_{i}^{\alpha_{i}+\delta_{i}+1}}{\Gamma(\alpha_{i}+\delta_{i}+2)|f_{i}(0,x(0)) - \theta_{i}\int_{0}^{\beta_{i}}f_{i}(s,x(s))\varphi_{i}(s)ds|}\right) \\ &\times \left(\sum_{j=1}^{n}\zeta_{ij}r + K_{i}\right) \\ &= \Phi_{i}\left(\sum_{j=1}^{n}\xi_{ij}r + H_{i}\right) + \Psi_{i}\left(\sum_{j=1}^{n}\zeta_{ij}r + K_{i}\right) \end{aligned}$$
(24)

for i = 1, ..., n.

So (24) implies that:

$$\|\mathcal{Q}_i x\|_{X_i} \leq \Phi_i \left(\sum_{j=1}^n \xi_{ij} r + H_i\right) + \Psi_i \left(\sum_{j=1}^n \zeta_{ij} r + K_i\right), i = 1, \dots, n.$$
 (25)

Hence,

$$\|\mathcal{Q}_i x\|_{\prod_{i=1}^n X_i} \leq r.$$
(26)

which leads to the conclusion that  $\mathcal{Q}_i(\mathfrak{B}_r) \subset \mathfrak{B}_r$ .

### S. Ferraoun and Z. Dahmani

**Step 2:** Let  $x, y \in X_i$ . For each  $t \in J$ , we have:

$$\begin{aligned} |\mathcal{Q}_{i}x(t) - \mathcal{Q}_{i}y(t)| &\leq |f_{i}(t, x(t))| \left( \frac{1}{\Gamma(\alpha_{i})} \int_{0}^{t} (t - \tau)^{\alpha_{i} - 1} |h_{i}(\tau, x(\tau)) - h_{i}(\tau, y(\tau))| d\tau \\ &+ \frac{1}{\Gamma(\alpha_{i} + \delta_{i})} \int_{0}^{t} (t - \tau)^{\alpha_{i} + \delta_{i} - 1} |k_{i}(\tau, x(\tau)) - k_{i}(\tau, y(\tau))| d\tau \\ &+ \frac{F_{i}|\theta_{i}|}{|f_{i}(0, x(0)) - \theta_{i} \int_{0}^{\beta_{i}} f_{i}(s, x(s))\varphi_{i}(s)ds|} \int_{0}^{\beta_{i}} |\varphi_{i}(s)| \\ &\times \left[ \frac{1}{\Gamma(\alpha_{i})} \int_{0}^{t} (t - \tau)^{\alpha_{i} - 1} |h_{i}(\tau, x(\tau)) - h_{i}(\tau, x(\tau))| d\tau \\ &+ \frac{1}{\Gamma(\alpha_{i} + \delta_{i})} \int_{0}^{t} (t - \tau)^{\alpha_{i} + \delta_{i} - 1} |k_{i}(\tau, x(\tau)) - k_{i}(\tau, y(\tau))| d\tau \right] ds \end{aligned}$$

$$(27)$$

Thanks to  $(\mathbf{H}1)$  and  $(\mathbf{H}2)$ , we get:

$$\begin{aligned} \|\mathcal{Q}_{i}x - \mathcal{Q}_{i}y\|_{X_{i}} &\leq F_{i}\left(\frac{1}{\Gamma(\alpha_{i})}\int_{0}^{t}(t-\tau)^{\alpha_{i}-1}d\tau\sum_{j=1}^{n}\xi_{ij}\|x_{j}-y_{j}\| \\ &+\frac{1}{\Gamma(\alpha_{i}+\delta_{i})}\int_{0}^{t}(t-\tau)^{\alpha_{i}+\delta_{i}-1}d\tau\sum_{j=1}^{n}\zeta_{ij}\|x_{j}-y_{j}\| \\ &+\frac{F_{i}|\theta_{i}|}{|f_{i}(0,x(0)) - \theta_{i}\int_{0}^{\beta_{i}}f_{i}(s,x(s))\varphi_{i}(s)ds|}\int_{0}^{\beta_{i}}\sup_{s\in J}|\varphi_{i}(s)| \\ &\times\left[\frac{1}{\Gamma(\alpha_{i})}\int_{0}^{t}(t-\tau)^{\alpha_{i}-1}d\tau\sum_{j=1}^{n}\xi_{ij}\|x_{j}-y_{j}\| \\ &+\frac{1}{\Gamma(\alpha_{i}+\delta_{i})}\int_{0}^{t}(t-\tau)^{\alpha_{i}+\delta_{i}-1}d\tau\sum_{j=1}^{n}\zeta_{ij}\|x_{j}-y_{j}\|\right]ds \end{aligned}$$
(28)

which becomes

$$\begin{aligned} \|\mathcal{Q}_{i}x - \mathcal{Q}_{i}y\|_{X_{i}} &\leq \left(\frac{F_{i}}{\Gamma(\alpha_{i}+1)} + \frac{F_{i}^{2}|\theta_{i}|\sup_{s\in J}|\varphi_{i}(s)|\beta_{i}^{\alpha_{i}+1}}{\Gamma(\alpha_{i}+2)|f_{i}(0,x(0)) - \theta_{i}\int_{0}^{\beta_{i}}f_{i}(s,x(s))\varphi_{i}(s)ds|}\right) \\ &\times \left(\sum_{j=1}^{n}\xi_{ij}\|x_{j} - y_{j}\|\right) \\ &+ \left(\frac{F_{i}}{\Gamma(\alpha_{i}+\delta_{i}+1)} + \frac{F_{i}^{2}|\theta_{i}|\sup_{s\in J}|\varphi_{i}(s)|\beta_{i}^{\alpha_{i}+\delta_{i}+1}}{\Gamma(\alpha_{i}+\delta_{i}+2)|f_{i}(0,x(0)) - \theta_{i}\int_{0}^{\beta_{i}}f_{i}(s,x(s))\varphi_{i}(s)ds|}\right) \\ &\times \left(\sum_{j=1}^{n}\zeta_{ij}\|x_{j} - y_{j}\|\right) \\ &= \Phi_{i}\left(\sum_{j=1}^{n}\xi_{ij}\|x_{j} - y_{j}\|\right) + \Psi_{i}\left(\sum_{j=1}^{n}\zeta_{ij}\|x_{j} - y_{j}\|\right) \end{aligned}$$

$$(29)$$

From (29), we have:

$$\|\mathcal{Q}_i x - \mathcal{Q}_i y\|_{X_i} \leq \left(\Phi_i \sum_{j=1}^n \xi_{ij} + \Psi_i \sum_{j=1}^n \zeta_{ij}\right) \times \left(\sum_{j=1}^n \|x_j - y_j\|\right)$$
(30)

for i = 1, ..., n.

Therefore,

$$\|\mathcal{Q}x - \mathcal{Q}y\|_{\sum_{i=1}^{n} X_{i}} \leq \sum_{i=1}^{n} \left(\Phi_{i} \sum_{j=1}^{n} \xi_{ij} + \Psi_{i} \sum_{j=1}^{n} \zeta_{ij}\right) \times \left(\sum_{j=1}^{n} \|x_{j} - y_{j}\|\right)$$

$$(31)$$

Since (**H**3) assures that  $\sum_{i=1}^{n} \left( \Phi_i \sum_{j=1}^{n} \xi_{ij} + \Psi_i \sum_{j=1}^{n} \zeta_{ij} \right) < 1$ , then the operator  $\mathcal{Q}$  is contractive. Then, according to Banach contraction principle, the system (1) has a unique solution on [0, 1].

## 4 Open Problems

It is to note that, in the future, we will be concerned with the problem (1) for studying the existence of solution via Leray Schauder theorem and/or Krasnoselskii fixed point lemma.

**Open problem A:** In this paper, we have presented some conditions to prove the existence and uniqueness of one solution for the problem (1). One first question that needs to be asked is the following:

Is it possible to change the Banach space of the above problem and to present some other conditions assuring the uniqueness of solution?

**Open problem B:** If we conserve the space and we change its associated norm, what can be the conditions that assure the uniqueness of solution for (1).

### References

- B. Ahmed, S. K. Ntouyas, and A. Alsaedi, Existence Results for a System of Coupled Hybrid Fractional Differential Equations, The Scientific World Journal, (2014), Article ID 426438, 6 pages.
- [2] S. Ali Khan, K. Shah, and R. Ali Khan, On Coupled System of Nonlinear Hybrid Differential Equation with Arbitrary Order, Matrix Science Mathematic, (2017), 1(2): 11-16.
- [3] L. Debanath, Recent Applications of Fractional Calculus to Science and Engineering, (2003), 3413-3442.
- [4] B.C. Dhage, On a Fixed Point Theorem in Banach Algebras with Applications, Applied Mathematics Letters, 18 (2005) 273-280.
- [5] M.A.E. Herzallah, and D. Baleanu, On Fractional Order Hybrid Differential Equations, Academic Press, San Diego, Calif, USA, (1999).
- [6] P. Kumlin, A Note on Fixed Point Theory, Mathematics Chalmers & GU, TMA 401/MAN 670 Functional Analysis 2003/2004.
- [7] H. Lu, S. Sun, D. Yang, and H. Tengi, Theory of Fractional Hybrid Differential Equations with Linear Perturbations of Second Type, Boundary Value Problems, (2013), 16 pages.
- [8] K. Nouri, M. Nazari, and B. Keramati, Existence Results for a Coupled System of Fractional Integro-Differential Equations with Time-Dependent Delay, J. Fixed Point Theory Appl., (2017), 17 pages.
- [9] G.A. Okeke, and M. Abbas, A Solution of Delay Differential Equations Via PicardKrasnoselskii Hybrid Iterative Process, Arabian Journal of Mathematics, (2017), 9 pages.

- [10] V. Patta, *Fixed Point Theorems and Applications*, Dipartimento di Matematica F. Brioschi, Politecnico di Milano.
- [11] I. Petr, Fractional Derivatives, Fractional Integrals, and Fractional Differential Equations in Matlab, Engineering Education and Research Using MATLAB, Technical University of Koice, Slovak Republic.
- [12] I. Podlubny, Fractional Differential Equations, Matrix Science Mathematic, (2017), 1(2): 11-16.
- [13] H. Sadeghian, H. Salarieh, A. Alasty, and A. Meghdari, On the control of chaos via fractional delayed feedback method, Computers and Mathematics with Applications, 62 (2011), 1482-1491.
- [14] V.V. Uchaikin, Fractional Derivatives for Physicists and Engineers, Volume I: Background and Theory, Nonlinear Physical Science, (2013).
- [15] Y. Zhaoa, S. Suna, Z. Hana, and Q. Li, Theory of Fractional Hybrid Differential Equations, Computers and Mathematics with Applications, 62 (2011), 1312-1324.